General Equilbrium Policy Analysis Lecture 1

Philip Schuster

at the Institute for Advanced Studies, Vienna

Vienna, April 13, 2015

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Outline

Introduction

Solving Deterministic Dynamic Perfect Foresight Models

A Simple Ramsey Model

Implementation on the PC

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Type of questions to be answered

- "What are the medium-run effects on GDP of revenue-neutrally shifting emphasize from the income to the value added tax in Spain?"
- "How much would the effective retirement age in Austria have to change over time to offset the effects from increasing population aging keeping all other pension system parameters constant?"
- "What are the consequences of increasing yearly migration flows to the United Kingdom to its public budgets?"

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Goals of the course

The goals of the course are...

- to introduce students to tools to answer policy questions such as those from the previous slide,
- to give a thorough understanding of how these tools work (look inside the black back instead of using front end modeling tools),
- and to do this step by step starting from the easiest model by adding model components sequentially,
- while giving a detailed documentation of the derivations and the computer codes.

Scope of the course

Focus on **dynamic computable general equilibrium** models mainly for **fiscal policy** simulation, in particular **transitional effects** of policies related to the **tax, social security and the pension system** with an emphasis on the household sector.

What is **not covered**:

- Aggregate shocks (DSGE).
- Certain idiosyncratic shocks (heterogenous agents literature).
- Inflation and monetary policy.
- Normative analyses.
- ► A detailed modeling of the production side (e.g. various sectors of the economy, often done as a static CGE exercise).

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Tentative outline of the course

- ► 1. Lecture: Introduction to solution algorithm, compute transitions for simple Ramsey model
- ► 2. Lecture: Introduction to OLG, Blanchard model in open economy with demographic change
- ► 3. Lecture: Endogenous labor supply, introduction of government and simulation of fiscal policy
- ► 4. Lecture: Unanticipated shocks, Walras' Law, effective taxation and progressivity and some principle comments on debugging and calibration
- ▶ 5. Lecture: Introduction to Gertler model and probabilistic aging.
- ► 6. Lecture: Introduction to Auerbach-Kotlikoff model, earnings-related pensions.
- ► 7. Lecture: Intergenerational distribution, calibration and possible extensions to the Auerbach-Kotlikoff model.

Material from https://sites.google.com/site/schusterphilip/: Manuscript (under continuous development), Slides (available before the lecture), MATLAB codes.

Time slots

- ▶ 1. Lecture: April 13, 2014, 16:30 18:30, Room IT A014
- I. Practice Session: April 15, 2014, 11:00 13:00, Room IT A014
- 2. Lecture: April 15, 2014, 16:30 18:30, Room IT A014
- 2. Practice Session: April 20, 2014, 10:30 12:30, Room IT A014
- 3. Lecture: April 20, 2014, 16:30 18:30, Room IT A014
- ▶ 4. Lecture: April 23, 2014, 16:30 18:30, Room IT A014
- ▶ 3. Practice Session: April 27, 2014, 11:00 13:00, Room IT A014
- ▶ 5. Lecture: April 27, 2014, 16:30 18:30, Room IT A014
- ▶ 6. Lecture: April 30, 2014, 16:30 18:30, Room IT A014
- ► 4. Practice Session: May 4, 2014, 11:00 13:00, Room IT A014
- 7. Lecture: May 4, 2014, 16:30 18:30, Room IT A014

Homework

- ▶ 1. Homework: assigned in 1. lecture, due before 2. lecture
- ▶ 2. Homework: assigned in 2. lecture, due before 3. lecture
- ▶ 3. Homework: assigned in 3. lecture, due before 5. lecture
- ▶ 4. Homework: assigned in 5. lecture, due before 7. lecture
- Final Project: assigned in 7. lecture, due by June 7.

Grading

Grading contributes 1/3 to the overall grade ('Applied Theory') and is based on three components

- ► Active participation in class (20%)
- ▶ Home exercises (in groups of 2-3 persons) (30%)
- ▶ Final project (in groups of 2-3 persons) (50%)

Tentative final project: A thorough calibration of the presented Auerbach-Kotlikoff model to an EU country of your choice. Simulation and interpretation of some defined reforms.

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Solving Deterministic Dynamic Perfect Foresight Models

Principle challenge is the computation of the transition:

- An agent's decision depends on her own future decisions as well as on future decisions of other agents (through prices!)
- Agents have to make time-consistent optimal decisions, i.e. ex-post they must not want to alter their choices (as they would with adaptive expectations, i.e. expectations based on the past)

Solution is a **path of prices** for all *n* markets under the condition that agents' **expectations are fully consistent** with the realizations.

Two options:

- One shot approach: Stack all equilibrium conditions of all periods together (including the time-consistency conditions) and solve for a path of prices for all markets in one go (using a standard numerical root finding algorithm)
- Split the problem in subproblems which is a more robust approach especially for large scale problems.

Fair Taylor algorithm 1/3

The **key for option 2** is to **separate** the tasks of finding market clearing prices for all periods and establishing time-consistency of agents' expectations. A prerequisite is that the **characterization of the solution** can be formulated in a **recursive way** (i.e. a system of first-order difference equations).

- ► We differentiate between:
 - A set of prices p
 - ► A set of predetermined, **backward looking** variables *B*, like the capital stock.
 - A set of **forward looking** variables *F*, like future wages or profits.
 - ► A set of **parameters** Z, like utility parameters, tax rates, etc.
- ▶ Define a **temporary equilibrium** in *t* as a price vector p_t which for a given guess about the foresight variables $F_{t+1|t}$ sets all excess demands to zero, i.e. $\zeta_n(p_t, B_t, F_{t+1|t}, Z_t) = 0, \forall n$.

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Fair Taylor algorithm 2/3



Solving for all temporary equilibria from t = 1 to t = T - 1 leaves us with an updated guess matrix, $\Lambda(F^i)$. In the **Fair-Taylor algorithm** the guess is updated according to

$$F^{i+1} = \psi \Lambda \left(F^i
ight) + (1 - \psi) F^i, \quad \psi \in (0, 1]$$

until convergence, i.e. $d(F^{i+1}, F^i) < \epsilon$.

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Fair Taylor algorithm 3/3

The steps of a full program for computing a transition path:

- 1. load model parameters
- 2. calibrate the model
- compute the Jacobian of the system Λ(·) (only necessary if generalized version of Fair-Taylor algorithm is used)
- 4. compute the **initial steady state** at t = 1
- 5. enter a **shock** to system, e.g. a policy reform
- 6. compute the **final steady state** at t = T
- 7. solve for the transition path
 - a) make a **guess** for *F*
 - b) compute a **path of temporary equilibria** starting from t = 1 to t = T 1
 - c) **update** the guess for F
 - d) repeat steps b) to c) until convergence

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Assumptions

To illustrate the solution algorithm we choose a simple Ramsey model with the following **assumptions**

- Single country, closed economy.
- Log felicity.
- Exogenous labor supply.
- Single representative firm owned by infinitely-lived representative household.
- ▶ 3 markets: homogenous good (numéraire), labor, and assets.

Household problem 1/2

$$U(A_t) = \max_{C_t} u(C_t) + \beta U(A_{t+1}), \quad \text{s.t.}$$
$$A_{t+1} = R_{t+1} [A_t + w_t L_0 - C_t]$$

where $R_{t+1} = 1 + r_{t+1}$. Note timing convention: Decisions and flows at the **beginning of the period**. Define the shadow price of assets as $\lambda_t = U'(A_t)$ then the **optimality** and **envelope** conditions are:

$$C_t: u'(C_t) = \beta \lambda_{t+1} R_{t+1}$$
$$A_t: \lambda_t = \beta \lambda_{t+1} R_{t+1}$$

Hence, the Euler equation (for log felicity) is

$$u'(C_t) = \beta R_{t+1} u'(C_{t+1}) \quad \Rightarrow \quad C_{t+1} = \beta R_{t+1} C_t$$

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Household problem 2/2

Recursively insert to rewrite the **budget constraint** as

$$A_{t} = C_{t} - w_{t}L_{0} + \frac{1}{R_{t+1}} \Big[C_{t+1} - w_{t+1}L_{0} + \frac{1}{R_{t+2}} \Big[C_{t+2} - w_{t+2}L_{0} + \dots \Big]$$

$$\Leftrightarrow \mathcal{W}_{t} = A_{t} + H_{t} \quad \text{where}$$

$$\mathcal{W}_{t} = C_{t} + \frac{1}{R_{t+1}} \Big[C_{t+1} + \frac{1}{R_{t+2}} \Big[C_{t+2} + \dots \\ H_{t} = w_{t} L_{0} + \frac{1}{R_{t+1}} \Big[w_{t+1} L_{0} + \frac{1}{R_{t+2}} \Big[w_{t+2} L_{0} + \dots \\ = w_{t} L_{0} + \frac{H_{t+1}}{R_{t+1}} \Big]$$

Insert the **Euler equation** in the definition of \mathcal{W}_t

$$\mathcal{W}_t = C_t + \frac{1}{R_{t+1}} \Big[C_t \beta R_{t+1} + \frac{1}{R_{t+2}} \Big[C_t \beta^2 R_{t+1} R_{t+2} + \dots \Big]$$
$$\mathcal{W}_t = C_t \cdot \sum_{s=t}^{\infty} \beta^{s-t} = C_t \cdot \Omega_t = C_t \cdot \frac{1}{1-\beta}.$$

Hence, the consumption function is

$$C_t = \Omega_t^{-1} (A_t + H_t).$$

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Firm problem 1/2

Maximize **firm value** (present value profits *V*):

$$\begin{split} V(K_t) &= \max_{l_t, L_t^D} \ \chi_t + \frac{V(K_{t+1})}{R_{t+1}}, \quad \text{s.t.} \\ \chi_t &= Y_t - w_t L_t^D - I_t \qquad (\text{per-period profits} = \text{dividend}) \\ Y_t &= f(K_t, L_t^D) \qquad (\text{hd1 production function}) \\ K_{t+1} &= (1 - \delta^K) K_t + I_t \qquad (\text{capital law of motion}) \end{split}$$

Define the shadow price of capital as $q_t = V'(K_t)$ then the two **optimality** and the **envelope** conditions are:

$$egin{aligned} & I_t: & q_{t+1} = R_{t+1} \ & L^D_t: & Y_{L^D_t} = w_t \ & \mathcal{K}_t: & q_t = Y_{\mathcal{K}_t} + rac{q_{t+1}}{R_{t+1}}(1-\delta^{\mathcal{K}}) \end{aligned}$$

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Firm problem 2/2

Theorem

Hayashi's theorem. Firm value and capital stock are related through Tobin's-q

$$q_t K_t = V_t, \quad \forall t$$

Proof

See manuscript.

Combine Hayashi's theorem with the law of motion and the optimality condition for investment to get a **relationship of investments and future profits**

$$I_t = rac{V_{t+1}}{R_{t+1}} - (1-\delta^{\mathcal{K}})\mathcal{K}_t$$

Temporary Equilibrium

In period t we know

- ► all parameters
- predetermined variable: K_t.
- guesses for forward looking variables: H_{t+1} and V_{t+1} .

Three markets have to clear: Labor $(L_t^D = L_0)$, assets $(A_t = V_t)$ and goods $(Y_t = C_t + I_t)$.

1.
$$L_t^D = L_0$$
 \Rightarrow w_t
2. $I_t = \frac{V_{t+1}}{R_{t+1}} - (1 - \delta^K)K_t$ \Rightarrow V_t, K_{t+1}
3. $H_t = w_t L_0 + \frac{H_{t+1}}{R_{t+1}}$ and $A_t = V_t$ \Rightarrow C_t
4. $Y_t = C_t + I_t$ \Rightarrow R_{t+1}

 R_{t+1} is found numerically (Ramsey) or using some algebra analytically (Ramsey_simple).

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Implementation on the PC

Some principle **notation**: A calibration value of variable X is scalar X0. The time vector of X from t = 1 to t = T is a row vector X.

Foresight variables: H and V, Predetermined: K

- ► We discuss code implementations: Ramsey and Ramsey_simple.
- We walk through all functions step by step.
- ▶ We look at 2 simple reforms:
 - $1.\,$ a negative shock to the capital stock and
 - 2. an exogenous increase in labor supply

and interpret the results.

Home exercises due before lecture 2: Ex. 2 and 3.